



AFRL-RX-WP-JA-2015-0212

**ON THE EIGENSTRAIN APPLICATION OF SHOT-
PEENED RESIDUAL STRESSES WITHIN A CRYSTAL
PLASTICITY FRAMEWORK: APPLICATION TO NI-
BASE SUPERALLOY SPECIMENS (POSTPRINT)**

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JULY 2015
Interim Report

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REPORT DOCUMENTATION PAGE				<i>Form Approved</i> OMB No. 0704-0188	
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1. REPORT DATE (DD-MM-YY) July 2015		2. REPORT TYPE Interim		3. DATES COVERED (From - To) 19 March 2014 – 29 June 2015	
4. TITLE AND SUBTITLE ON THE EIGENSTRAIN APPLICATION OF SHOT-PEENED RESIDUAL STRESSES WITHIN A CRYSTAL PLASTICITY FRAMEWORK: APPLICATION TO NI-BASE SUPERALLOY SPECIMENS (POSTPRINT)				5a. CONTRACT NUMBER In-House	
				5b. GRANT NUMBER	
				5c. PROGRAM ELEMENT NUMBER 62102F	
6. AUTHOR(S) See back.				5d. PROJECT NUMBER 4349	
				5e. TASK NUMBER	
				5f. WORK UNIT NUMBER X0W6	
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) See back.				8. PERFORMING ORGANIZATION REPORT NUMBER	
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES) Air Force Research Laboratory Materials and Manufacturing Directorate Wright-Patterson Air Force Base, OH 45433-7750 Air Force Materiel Command United States Air Force				10. SPONSORING/MONITORING AGENCY ACRONYM(S) AFRL/RXCM	
				11. SPONSORING/MONITORING AGENCY REPORT NUMBER(S) AFRL-RX-WP-JA-2015-0212	
12. DISTRIBUTION/AVAILABILITY STATEMENT Distribution Statement A. Approved for public release: distribution unlimited.					
13. SUPPLEMENTARY NOTES Journal article published in <i>International Journal of Mechanical Sciences</i> 100 (2015) 195-208. The U.S. Government is joint author of the work and has the right to use, modify, reproduce, release, perform, display or disclose the work. This report contains color. The final publication is available at http://dx.doi.org/10.1016/j.ijmecsci.2015.06.020 .					
14. ABSTRACT Shot-peening-induced compressive residual stresses are often introduced in Ni-base superalloy components to help prevent or retard surface fatigue crack initiation and early growth at near surface inclusions. In certain cases these compressive residual stresses can shift the fatigue crack initiation site from surface to sub-surface locations. However, the ability to computationally predict the improvement in fatigue life response and scatter due to induced compressive residual stresses are lightly treated in the literature. To address this issue, a method to incorporate shot-peened residual stresses within a 3D polycrystalline microstructure is introduced in this work. These residual stresses are induced by a distribution of fictitious orquasi-thermal expansion eigenstrain as a function of depth from the specimen surface. Two different material models are used, a J_2 plasticity and a crystal plasticity model. First, the J_2 plasticity model with combined isotropic and kinematic hardening is used to determine the distribution of quasi-thermal expansion eigenstrain as a function of depth from the surface necessary to induce the target residual stress profile within the microstructure. This distribution of quasi-thermal expansion eigenstrain is then used within a crystal plasticity framework to model the effect of microstructure heterogeneity on the variability in residual stresses among multiple instantiations. This model is verified with experimental X-ray diffraction (XRD) data for scatter in residual stresses for both the initial microstructure and after a single load/unload cycle.					
15. SUBJECT TERMS crystal plasticity, Ni-base superalloys, IN100, residual stresses, eigenstrain					
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT: SAR	18. NUMBER OF PAGES 12	19a. NAME OF RESPONSIBLE PERSON (Monitor) William D. Musinski 19b. TELEPHONE NUMBER (Include Area Code) (937) 255-0485
a. REPORT Unclassified	b. ABSTRACT Unclassified	c. THIS PAGE Unclassified			

REPORT DOCUMENTATION PAGE Cont'd

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On the eigenstrain application of shot-peened residual stresses within a crystal plasticity framework: Application to Ni-base superalloy specimens



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ARTICLE INFO

Article history:

Received 20 February 2015

Received in revised form

22 May 2015

Accepted 29 June 2015

Available online 8 July 2015

Keywords:

Crystal plasticity
Ni-base superalloys
IN100
Residual stresses
Eigenstrain

ABSTRACT

Shot peening induced compressive residual stresses are often introduced in Ni base superalloy components to help prevent or retard surface fatigue crack initiation and early growth at near surface inclusions. In certain cases these compressive residual stresses can shift the fatigue crack initiation site from surface to sub surface locations. However, the ability to computationally predict the improvement in fatigue life response and scatter due to induced compressive residual stresses are lightly treated in the literature. To address this issue, a method to incorporate shot peened residual stresses within a 3D polycrystalline microstructure is introduced in this work. These residual stresses are induced by a distribution of fictitious or quasi thermal expansion eigenstrain as a function of depth from the specimen surface. Two different material models are used, a J_2 plasticity and a crystal plasticity model. First, the J_2 plasticity model with combined isotropic and kinematic hardening is used to determine the distribution of quasi thermal expansion eigenstrain as a function of depth from the surface necessary to induce the target residual stress profile within the microstructure. This distribution of quasi thermal expansion eigenstrain is then used within a crystal plasticity framework to model the effect of microstructure heterogeneity on the variability in residual stresses among multiple instantiations. This model is verified with experimental X ray diffraction (XRD) data for scatter in residual stresses for both the initial microstructure and after a single load/unload cycle.

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1. Introduction

1.1. Motivation for modeling residual stresses

The beneficial effects of compressive surface residual stresses on high cycle fatigue (HCF) response have been well documented in the literature [1–4]. For Ni base superalloys, a shift from surface dominated to subsurface dominated fatigue crack initiation sites exists for the transition from low cycle fatigue (LCF) to HCF regimes [5–9]. A similar surface to subsurface transition has been reported for titanium alloys [10,11] and high strength steels [12,13]. In the transition fatigue regime (cycles to failure, $N_f \sim 1 \times 10^4$ – 5×10^5 cycles), subsurface initiated fatigue cracks tend to require more cycles to failure as compared to surface initiated

fatigue cracks [5]. Accordingly, surface compressive residual stresses are often introduced in Ni base superalloy components to help prolong/retard fatigue crack initiation [14] and early growth at near surface inclusions and potentially shift fatigue crack initiation sites from surface to subsurface locations [1,2] to increase fatigue life. However, compressive residual stresses are usually only useful in the transition fatigue and HCF ($N_f > 5 \times 10^5$ cycles) regimes since residual stress relaxation at higher applied stress/strain values can eliminate the effectiveness of compressive residual stresses on fatigue life [14–17].

Compressive surface residual stresses can be applied via multiple techniques (shot/gravity peening, low plasticity burnishing, laser shock peening, etc. [18]). Shot peening is the most commonly used technique in industry to induce compressive residual stresses at the surface, and is the focus of this residual stress study. During the shot peening process multiple high velocity shot beads impact the surface forming multiple indentations and inhomogeneous compressive elastic/plastic deformation of the near surface layer. As such, the resulting residual stress profile is dictated by (1) the

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interaction between multiple indentations, (2) localized constrained compression, (3) strain rate sensitivity and elastic/plastic response of the material, and (4) local microstructure. In modeling, these discrete impingement events can either be modeled explicitly or idealized as a collective elastic/plastic constrained compressive loading/unloading event as schematically shown in Fig. 1. The idealization of the multiple impingement shot peening process as a single deformation event is adopted in this paper.

While the influence of residual stress on fatigue life has been reported extensively in the literature, the ability to computationally predict the improvement in fatigue resistance and change of scatter due to induced compressive residual stresses are lacking in the literature. A significant effort in modeling inclusion and residual stress effects in shot peened martensitic gear steels was undertaken by Prasannavenkatesan et al. [19–22]. They considered separate 3D finite element method (FEM) models at discrete depths subjected to the required amount of compressive load/unload strain to induce the required residual stress profile at each particular depth. The simulated inclusion sizes ($< 10 \mu\text{m}$) were small compared to the overall 3D FEM model dimensions, so the gradient in applied stress and residual stress over the inclusion was considered to be negligible in their analysis. Alternatively, inclusion sizes in powder metallurgy polycrystalline Ni base superalloy IN100 are on the order of $10\text{--}100 \mu\text{m}$ [6,23,24]. For inclusions of these sizes, the gradient in residual stress (RS) field due to shot peening (Ref. RS profile in [25]) can have a significant effect on stress/strain response and should be considered when analyzing inclusion and RS effects in Ni base superalloys. Therefore, a simulation approach that accounts for the entire distribution of residual stress, and not just at discrete surface depths, is warranted. Hence, we aim to develop a framework to assess (1) the effect of microstructure on the entire residual stress profile due to shot peening and (2) the effect of cyclic loading on residual stress relaxation in polycrystalline Ni base superalloy components.

This section begins with a brief overview of previous methods to impose residual stresses within components. Next, the eigen strain application of residual stresses within a FEM framework is discussed and a J_2 plasticity model is presented for calibrating this model. Finally, the method by which crystal plasticity is incorporated is presented with results for variability of initial residual stress and retained residual stress due to a single load/unload sequence.

1.2. Previous methods for simulated application of residual stresses

Techniques to simulate the shot peening process can be divided into two methods: (1) Simulation of the impact response between the shot bead and the shot peened surface by quasi static or explicit dynamic analyses to predict the resulting residual stress

and/or Almen intensity as a function of shot peening parameters (shot size, speed, coverage, material properties, incident angles, etc.) [26–42] and (2) Simulation of the overall induced mechanical response due to shot peening through a deformation process [20,43,44]. Some examples of relevant works regarding these two methods are discussed below.

1.2.1. Simulation of single and multiple impact events

The first means to model the high velocity impact shot peening process focused on single impact events on an elastic plastic target substrate. Chen and Hutchinson [27,28] and Boyce et al. [26] found that explicit dynamic simulations incorporating effects of strain rate sensitivity, inertia, and elastic wave propagation resulted in a better prediction of residual stresses than quasi static analyses. Frija et al. [29] used an energy equivalence expression and 3D quasi static FEM analysis to find good correlation between the predicted residual stress along the shot bead impact centerline and experiments. Zion and Johnson [34] studied the impact of a hard and soft shot bead and a high strength steel and found that the most highly significant input factor was the value of friction coefficient assumed between the shot bead and target material. While these single impact simulations can unveil key relationships between shot peen input (e.g. shot diameter, impact velocity, incident angle) and residual stress output [32], multiple impact events should be used to simulate more realistic peening conditions.

One means to model multiple impacts is to combine discrete element modeling (DEM) and FEM to determine RS profile. DEM simulates spatial interactions/collisions among multiple discrete particles within the shot stream. DEM exports particle/substrate impact velocity, location, and contact forces into a FEM model to calculate resulting plastic strains and residual stresses. Multiple researchers [39–42] have used this combined DEM FEM approach to link the effect of complex part geometry on the overall shot peening process, including the effects of impact angle, impact density, and coverage on location specific residual stress formation.

These combined DEM FEM simulations of multiple impingement events are certainly noteworthy. However, it is hard to discern how much variability in local residual stress is attributed to (1) the localized inhomogeneous deformation due to the stochastic impingement events inherent in the shot peening process and (2) the effect of local microstructure, especially grain orientation. Therefore, to isolate the effect of local microstructure, we propose to use a uniform average “amount of impingement” within a crystal plasticity finite element model. In this approach, the individual shot peen events that were modeled in the previous method(s) are not modeled. Instead, the resulting material deformation and hardening states due to shot peening are (1) induced explicitly within an implicit or explicit FEM model and (2) used as initial conditions for subsequent relaxation/fatigue analysis simulations.

1.2.2. Techniques to induce overall mechanical response due to shot peening

One way to induce residual stresses explicitly within an FEM model is to deform the FEM model in displacement controlled constrained compression. This method mimics the collective mechanical means in which biaxial residual stresses are imposed within a component during the shot peening process and traces the evolution of the material state throughout the deformation process. For example, Prasannavenkatesan et al. [20,21] used a simple displacement controlled method in conjunction with isotropic plasticity [20] and polycrystal plasticity [21] to induce residual stresses [20] and reproduce experimental trends in

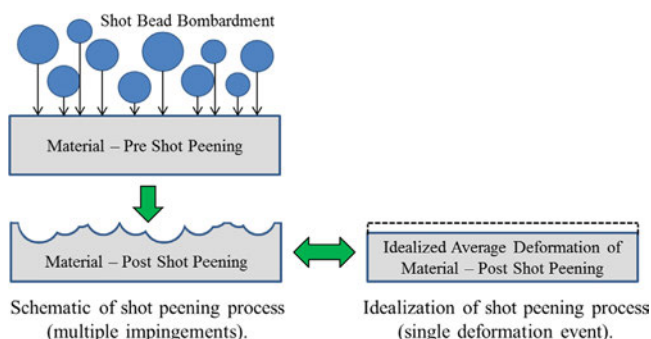


Fig. 1. Schematic showing idealization of shot peening process as a single deformation event.

residual stress relaxation [21] due to HCF cyclic bending of a martensitic gear steel. For these analyses, individual 3D FEM models were used at discrete depths and subjected to the required amount of compressive load/unload strain to induce the required residual stress profile at each particular depth. This displacement controlled method presented by Refs. [20,21] is best used for simulated application of residual stresses to the surface of a smooth planar specimen with well defined boundary and loading conditions.

An alternative means to initialize residual stresses within a FEM model is to use the residual stress and material hardening states for target initial conditions. For example, Buchanan et al. [25,45] initialized their material model with an initial material hardening state (effective plastic strain, backstress) and residual stress state based on experimental XRD and cold work measurements at different depths in a Ni base superalloy IN100 material [45]. Similarly, Benedetti et al. [46,47] imposed initial local yield strength and hardening variables at different depths based on the experimental microhardness measurement at that depth. Additionally, the initial residual stress profile was induced by introducing an experimentally fit eigenstrain distribution within the FEM model. The method of introducing eigenstrains within an FEM model to produce residual stresses is covered in more detail next.

1.2.3. Eigenstrain method of imposing residual stresses

Eigenstrains have long been used to model micromechanical misfit strains that are not associated with globally/externally applied mechanical loading. Some examples where eigenstrains are used include internal stresses due to inclusions/particles or fibers [48], differences in coefficient of thermal expansion of different phases/layouts [49], phase transformations [50], and heat treatment effects [51]. Several authors have used the eigenstrain method to model/reconstruct residual stresses induced by shot peening [44,52–54], laser shock peening [55–61], and welding [62–66]. For shot peening analysis, the amount of residual stress induced as a function of depth can be controlled by specifying spatial distributions of thermal eigenstrains. The actual residual stress application process is nominally isothermal, so the applied temperature change and thermal expansion eigenstrains are fictitious; they are merely introduced as a means to induce residual stresses within a component under isothermal conditions.

The main challenge of this approach is determining the correct eigenstrain distribution required to produce a given residual stress profile. General solutions/frameworks to the so called “inverse eigenstrain problem” have been developed/presented by many authors [44,52,53,67–69]. Universally, these approaches assume that the eigenstrain distribution can be reconstructed as a superposition of a truncated series of basis functions, i.e.,

$$\varepsilon^*(x) = \sum_{i=1}^N c_i \xi_i(x) \quad (1)$$

In this equation, N is the number of basis functions, $\xi_i(x)$, and c_i are the coefficient multipliers for each basis function. The benefit of this model is that one is at liberty to choose the total number of basis functions and the form of each basis function; as a result, there are multiple sets of basis functions that can describe a given eigenstrain distribution. For example, one could use a series of smooth basis functions [67–69], multiple polynomials [44], or even a superposition of multiple kernel density functions including triangular functions [53] or normal distribution functions [52] as the overall eigenstrain distribution estimator. Regardless of the functional form, the most important factor that should be considered is how to solve for the basis function coefficients and

whether the given eigenstrain distribution is able to reconstruct the desired residual stress profile. For example, Korsunsky [44] used axisymmetric plate theory to analytically find stresses and deformations arising due to peening and found the necessary eigenstrain as a function of plate depth using polynomial functions as basis functions.

Methods that incorporate both the dynamic material response during residual stress application and the subsequent effect that these residual stresses have on material behavior typically require separate analyses due to different time scales (dynamic shot/laser peen process versus quasi static LCF/HCF/creep loading). For example, Achintha et al. [55–57] combined explicit dynamic and implicit FEM analyses to model the laser shock peening in a Ti 6Al 4V alloy using an eigenstrain approach and an assumed elastic perfectly plastic material model. They found that although eigenstrain distributions were similar for different specimen thicknesses, the resulting residual stresses were quite different among different specimen thicknesses.

1.3. Objectives, scope and limitations of current work

The previous eigenstrain methods mentioned in the foregoing all suffer from the same shortcomings: they used simple elastic plastic models that are unable to determine the effect of local/random microstructure (e.g. grain size/orientation) on residual stress profile variability and residual stress relaxation. Hence, the objective of this paper is to develop a combined eigenstrain and crystal plasticity finite element simulation approach to address this critical need.

There are many approximations made with regard to the actual shot peening process in our simulations. The process of shot peening involves multiple random shot indentations inducing surface roughness (cf. [15,47,70]). As stated previously, we do not model individual shot peening events. Rather, the collective shot peening process is modeled as a uniform, quasi static displacement event (cf. Fig. 1) that spatially varies as a function of surface depth. The variability in residual stress comes into play due to the microstructure, not due to incomplete coverage or random/sporadic shot locations. In practice, the XRD residual stress measurements are averaged over the irradiated area determined by the size of the X ray beam. The experimental XRD average residual stress data used for comparison in this study was found over an irradiated area of 3 mm × 5 mm [45], which encompasses over 10,000 grains. Therefore, the highly localized variations in residual stresses due to surface undulations are averaged out for the reported XRD residual stress data. Therefore, we do not simulate the random surface undulations due to the multiple surface impingements induced during the shot peening process. Instead, we impose a uniform “amount of impingement” in each surface layer by means of an applied eigenstrain.

Free surface effects with respect to in plane stress components were neglected/avoided by assuming that the finite element material is from the center of the specimen. The increased hardening of the surface layer of the shot peened material is accounted for in the crystal plasticity finite element model via an increase in dislocation density (and the subsequent increase in yield strength [71]) at the surface.

It should also be noted that the intense amount of near surface cold working and dense dislocation network produced during shot peening can invoke near surface plasticity induced refinement of the microstructure [45,70]. This microstructure refinement is not accounted for in this work. Thus, the purpose of our model is to simulate the overall induced mechanical response due to shot peening, rather than individual impact events or grain refinement.

2. Methodology for imposing residual stresses using eigenstrain approach

The methodology used to impose residual stresses within an eigenstrain framework and its extension to the crystal plasticity finite element method are covered in this section. The quasi thermal expansion distribution can be optimized to fit any targeted/measured residual stress profile. The actual process is isothermal, so the thermal expansion fields are simply used to induce plastic strain gradients and residual stresses. Additionally, this technique has the added benefit that it can be used for more complex material response (e.g., crystal plasticity) and more complex geometries (e.g., notches).

2.1. Material model

2.1.1. Experiments used to calibrate model

During the shot peening process, equibiaxial compressive residual stresses are introduced near the surface due to constrained plastic deformation. To satisfy equilibrium, tensile stresses form within the subsurface of the material. These tensile stresses may decay with increasing depth for thicker specimens [72–74] or approach a steady state value within the bulk of the material for thinner specimens [25,45]. For example, Buchanan et al. [25] performed residual stress relaxation studies of 2 mm thick powder metallurgy (PM) Ni base superalloy IN100 (25 μm average grain size) specimens that were shot peened to an Almen intensity of 6 A. The residual stress profile given in [25] contains average residual stress values measured over a 3 mm \times 5 mm irradiated X ray region at given depths from the surface. These measured average residual stress values were fit to a curve of the form [45]

$$\sigma_{RS}(x) = [(\sigma_s - \sigma_{int}) + C_1 x] \exp(-C_2 x) + \sigma_{int} \quad (2)$$

where the least square values of $\sigma_s = 879.0$, $\sigma_{int} = 205.7$, $C_1 = 67028$, and $C_2 = 20.89$ were determined by Buchanan [45] to fit the experimental residual stress data as a function of depth (x) from the surface. Eq. (2) assumes that the residual stress approaches a steady state internal value of σ_{int} with increasing depth (x) and is applicable for depth values from the surface ($x=0$) to half depth ($x=1$ mm), where the condition of half symmetry is assumed.

Since the work of Buchanan [45] contains information on both the initial residual stress curve and relaxation of residual stresses with fatigue loading and is applied to thinner (2 mm) specimens, we will use Eq. (2) for the initial residual stress curve. Additionally, we limit our computational specimen thickness to 2 mm to ensure that it is consistent with experiments.

2.1.2. Isotropic J_2 plasticity model

A rate independent J_2 plasticity finite element model with combined isotropic/kinematic hardening was used to calibrate the quasi thermal residual stress application approach. The resulting calibrated eigenstrain distribution was later used as an input for a crystal plasticity finite element method (CPFEM) model. The J_2 plasticity model employed is an existing ABAQUS [75] material model that employs the Von Mises yield surface $F = f(\sigma - \alpha) - \sigma_{ys} = 0$, where $F = 0$ during plastic flow, σ and α are the stress and back stress tensors, respectively, and σ_{ys} is the Von Mises equivalent yield strength. The function f is given by $f(\sigma - \alpha) = \sqrt{\frac{3}{2}(\underline{\sigma} - \underline{\alpha}) : (\underline{\sigma} - \underline{\alpha})}$ where $\underline{\sigma}$ is the deviatoric stress tensor. An associated flow rule is assumed as $\dot{\underline{\epsilon}}^p = \dot{\underline{\epsilon}}^p \frac{\partial F}{\partial \underline{\sigma}}$. Here, $\dot{\underline{\epsilon}}^p$ is the plastic strain rate tensor and $\dot{\underline{\epsilon}}^p = \sqrt{\frac{2}{3}} \dot{\underline{\epsilon}}^p : \dot{\underline{\epsilon}}^p$ is the equivalent plastic strain rate. Cyclic hardening of the yield stress is accounted

for by the evolution of isotropic hardening via $\sigma_{ys} = \sigma_0 + \kappa_s [1 - \exp(-b \dot{\underline{\epsilon}}^p)]$ [76,77], where σ_0 is the yield stress at zero plastic strain, κ_s is the maximum change in the size of the yield surface, and b defines the rate at which cyclic hardening occurs. The evolution of the back stress tensor is characterized by $\dot{\underline{\alpha}}_k = \frac{c_k}{\sigma_{ys}} (\underline{\sigma} - \underline{\alpha}) \dot{\underline{\epsilon}}^p - r_k \underline{\alpha}_k \dot{\underline{\epsilon}}^p$ [20,75].

For this study, we employ $k=2$ backstress terms ($c_1=280,900$, $c_2=10,178$, $r_1=1163.8$, $r_2=55.65$) to facilitate better stress strain fitting at lower ($k=1$) and higher ($k=2$) strains. This computational model was matched to experimental stress strain data [78] for a coarse grained IN100 Ni base superalloy microstructure. The resulting stress strain plot comparing the computational and experimental data is illustrated in Fig. 2. The optimized isotropic/kinematic hardening parameters for this J_2 plasticity model are listed in the upper left hand corner inset of the Figure. As shown in this Figure, this J_2 plasticity model mimics the cyclic stress strain behavior well for a very complex loading history. Thus, this J_2 plasticity model is deemed sufficient for the calibration of the thermal expansion eigenstrain method to impose residual stresses in smooth specimen components. These results are presented later.

2.1.3. Polycrystal plasticity framework with quasi thermal expansion eigenstrain

This section describes how the concept of quasi thermal expansion eigenstrain finite element method (covered in the next section) was extended in the context of polycrystal plasticity for purposes of imposing a target subsurface residual stress field due to shot peening. The benefit of crystal plasticity relative to the J_2 plasticity model is that it can characterize microstructure variability; a number of different statistically representative microstructure instantiations can be simulated to address the probabilistic fatigue strain life distribution. The goal of this study was to develop a framework to induce a full residual stress profile within a crystal plasticity finite element framework to account for this microstructure variability. Such a framework can be used to assess the effectiveness of shot peening in suppressing near surface crack initiation from inclusions located near to the surface of smooth specimens [79].

To incorporate thermal expansion eigenstrain within the crystal plasticity finite element method under ostensibly isothermal loading conditions, a “quasi” thermal expansion contribution must be included within the deformation gradient. As shown in Fig. 3, the total deformation gradient is assumed to be multiplicatively

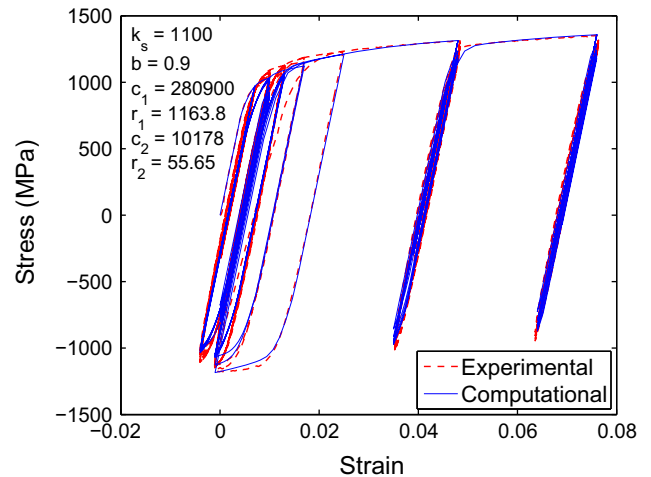


Fig. 2. Comparison of J_2 plasticity model in ABAQUS to experimental data of a coarse grain IN100 cycled at 650 °C. Experimental data are from Ref. [78].

decomposed via

$$\mathbf{F} = \mathbf{F}^e \cdot \mathbf{F}^p \cdot \mathbf{F}^\theta \quad (3)$$

where \mathbf{F}^e denotes elastic distortion and rigid body rotation of the crystal lattice, \mathbf{F}^p accounts for plastic deformation through dislocation glide along crystallographic planes, and \mathbf{F}^θ constitutes thermal expansion. It is noted that temperature change is introduced *only* to produce an eigenstrain field to induce initial residual stresses from associated elastic plastic deformation. No other properties need be temperature dependent. Isotropic, linearized thermal expansion is assumed, i.e.

$$\mathbf{F}^\theta = \sqrt{1 + 2\alpha\Delta\theta} \mathbf{I} \quad (4)$$

where α is the isotropic thermal expansion coefficient, $\Delta\theta$ is the change in temperature, and \mathbf{I} is the second rank identity tensor. The form of Eqn. (4) was chosen so that the linearized form of the Green finite strain tensor due to thermal expansion, \mathbf{E}^θ , is [80]

$$\mathbf{E}^\theta = \frac{1}{2} \left([\mathbf{F}^\theta]^T \cdot \mathbf{F}^\theta - \mathbf{I} \right) = \alpha\Delta\theta \mathbf{I} \quad (5)$$

The rest of the microstructure sensitive crystal plasticity equations for modeling deformation behavior of a coarse grain IN100 at 650 °C follow those outlined by Przybyla and McDowell [70]. A detailed description of the CPFEM model is omitted in this paper to maintain brevity. We only highlight the incorporation of a quasi thermal expansion deformation gradient (\mathbf{F}^θ) in this section to distinguish what is new/unique in the current CPFEM model relative to the previous IN100 model. More details on the development of the IN100 model and the numerical implementation technique in ABAQUS can be found in the work of Shenoy et al. [78,81] and McGinty [82], respectively.

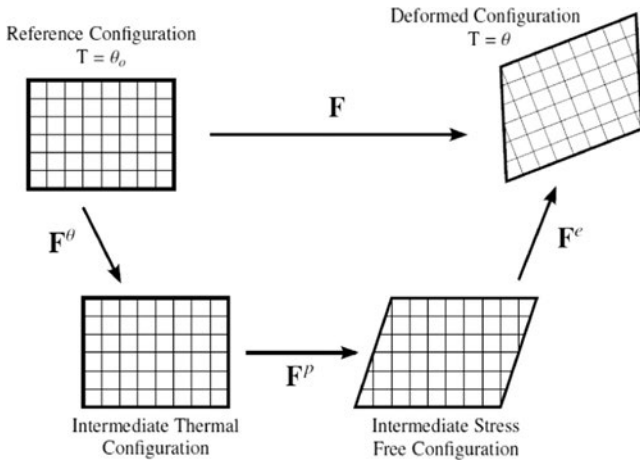


Fig. 3. Multiplicative decomposition of the deformation gradient, including quasi-thermal expansion.

2.2. Finite element model imposition of eigenstrain field

To simulate the material stress state after the shot peening process, a finite element model is used and calibrated to the experimental residual stress XRD data reported by Buchanan et al. [14,25,45,83,84] on a supersolvus PM Ni base superalloy IN100 with an average grain size of 25 μm that was shot peened to a Almen intensity of 6 A. A quasi thermal method of application of residual stresses is chosen in this work because it is easy to apply and calibrate and it is easily extended to more complex models for material response (e.g., crystal plasticity) and more complex geometries (e.g., notches).

2.2.1. Application to J_2 plasticity model

The general methodology for quasi thermal application of residual stresses to a smooth specimen is shown in Figs. 4 and 5 and can be summarized as follows:

1. **Initial configuration:** Fig. 4 shows the finite element model used to simulate residual stress application to a smooth specimen. The experimental smooth specimen [45] had a nominal gage section length, width, and thickness of $y=20\text{ mm}$, $z=10\text{ mm}$ and $x=2\text{ mm}$, respectively (see Fig. 4 for x , y , and z directions). Similar to the finite element model employed by Buchanan et al. [25,45], a small portion in the center of this gage section was used for the finite element model. Half symmetry within the depth (x dimension) of the material was employed so that the overall dimensions of the finite element model for J_2 plasticity simulations were $x_{dim}=1\text{ mm}$, $y_{dim}=34\text{ }\mu\text{m}$, and $z_{dim}=34\text{ }\mu\text{m}$. For eigenstrain distribution calibration, the finite element model was divided into many 2.5 μm thick finite elements, as shown in the rightmost image in Fig. 4. It should be noted that since the compressive region of residual stress field is very thin (x depth $\sim 200\text{ }\mu\text{m}$) and there is a high gradient of residual stress with depth, a very fine finite element thickness of 5 μm is required near the surface to provide convergence of the FEM response. Buchanan [45] reported a similar FEM mesh size requirement for convergence. In this work, a finer mesh of 2.5 μm was used to provide more eigenstrain distribution data points (black dots in Fig. 5) to improve functional form fitting; this fitting is covered later. Each finite element was assigned a given quasi thermal expansion coefficient α_j and J_2 plasticity material properties. The initial distribution of α_j values was assigned so that the resulting residual stress values were within $\pm 250\text{ MPa}$ from the target residual stress profile at a given depth to avoid any numerical instabilities in the numerical optimization scheme described below.
2. **Eigenstrain application:** with all surfaces constrained from normal displacement, an eigenstrain ($\epsilon_{therm,j}^* = \alpha_j \Delta T$) is introduced within the model as shown in the upper left hand corner

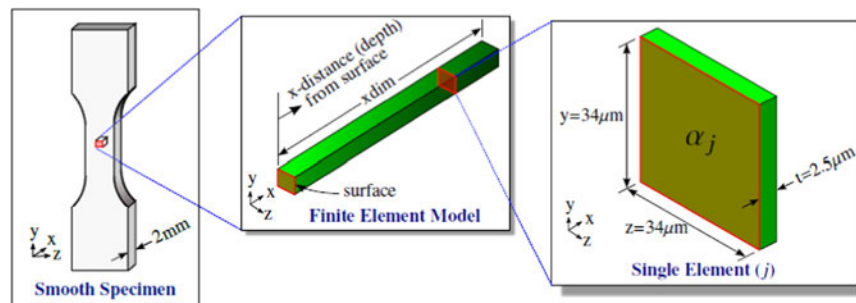


Fig. 4. Finite element model used to apply residual stress to a smooth specimen.

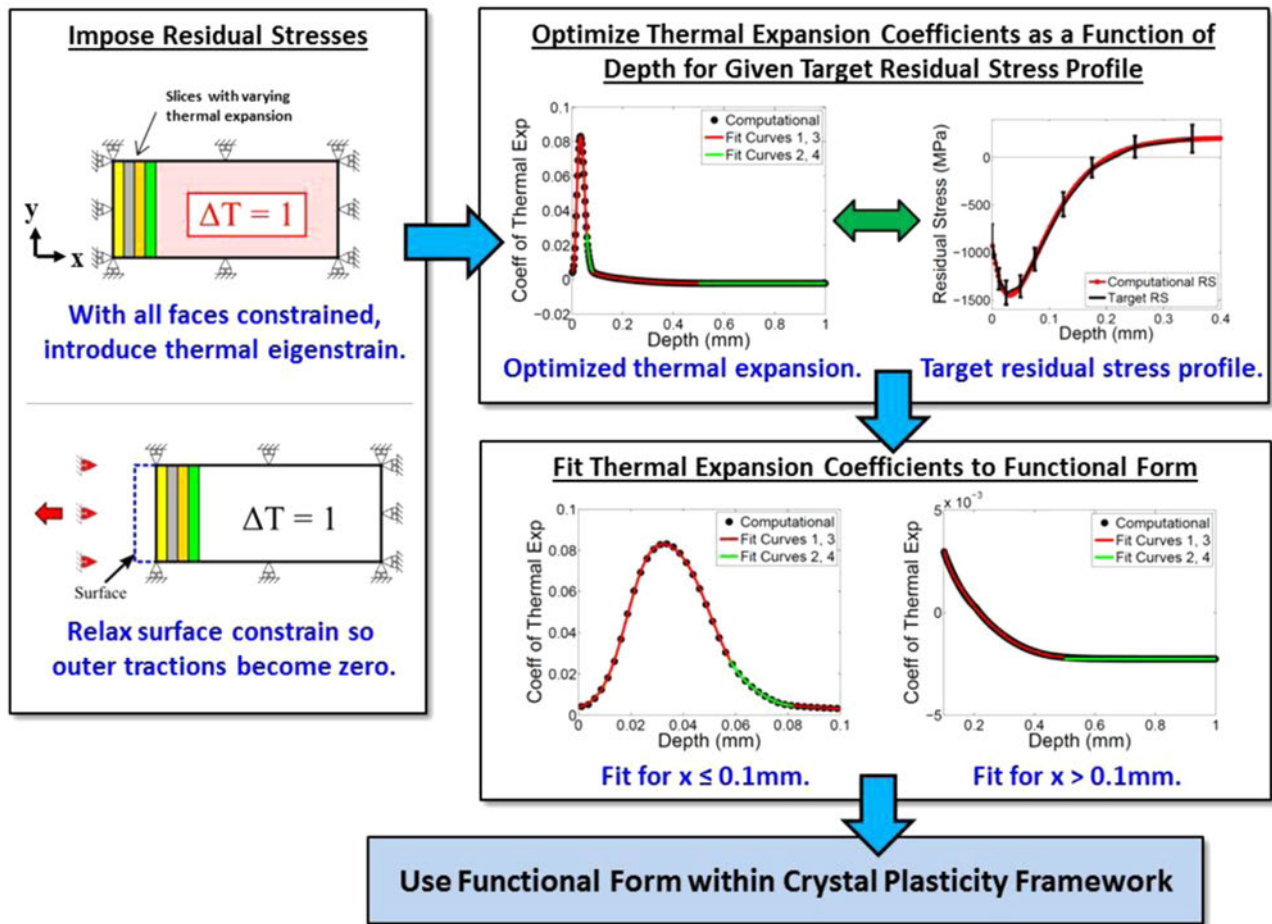


Fig. 5. Methodology for quasi-thermal application of residual stresses to a smooth specimen.

of Fig. 5. It should be noted that an arbitrary value of $\Delta T = 1$ was applied uniformly throughout the whole specimen, with out loss of generality, since temperature is not a physical field variable during the imposition of residual stress.

3. *Release surface constraint*: the surface constraint at $x=0$ is removed to simulate the spring back of the material after shot bead impact (cf. lower left hand portion of Fig. 4). This step is required to relax the stress component normal to the surface so that $\sigma_{xx} \sim 0$, which is representative of the near surface stress state at the end of the shot peening process [20]. This relaxation step is analogous to the “unload” step in the displacement controlled method of residual stress application presented by Prasannavenkatesan et al. [20].
4. *Optimization of thermal expansion coefficients*: a secant root finding method [85] is used in conjunction with the FEM model to optimize the spatial distribution of thermal expansion parameters to fit the experimental residual stress profile.
5. *Fit thermal expansion coefficients to functional form*: Gaussian probability density functions and polynomials are used to fit the optimized thermal expansion coefficient as a function of depth from the surface. More details on this functional form and how it is used within the crystal plasticity framework are covered in the following.

2.2.2. Fitting thermal expansion coefficient to functional form

The right hand side of Fig. 5 shows the required thermal expansion as a function of x distance (depth) from the surface that is used to replicate the target residual stress profile shown in the upper right hand portion of Fig. 5. The black dots in Fig. 5 show the optimized thermal expansion coefficient found using

the secant root finding method and the red and green solid lines show the functional form fitting of these computationally optimized thermal expansion coefficients. The top middle plot in Fig. 5 displays the entire distribution of thermal expansion coefficient as a function of x distance from the surface. The bottom right two plots in Fig. 5 illustrate zoomed in versions of the fitting of the required thermal expansion coefficient to the piecewise functional forms described below. A piecewise smooth functional form was required so that the thermal expansion coefficients can be defined independent of mesh size and so that this functional form could be used as an input for the crystal plasticity model. The thermal expansion function, $\alpha(x)$, was split into 4 sections:

1. $x < 0.058$ mm: this section of the curve was fit using a super position of two Gaussian probability density functions (PDFs). A similar description of using two Gaussian PDFs was demonstrated in [52] to describe the eigenstrains induced by shot peening a GW103 magnesium alloy. The functional form used to fit the thermal expansion coefficients at $x < 0.058$ mm is

$$\alpha(x) = A \exp \left[\frac{(x - \mu_B)^2}{2\sigma_B^2} \right] + D \exp \left[\frac{(x - \mu_E)^2}{2\sigma_E^2} \right] + Gx + H \quad (6)$$

2. $0.058 \text{ mm} \leq x < 0.082$ mm: this section was fit using a 5th order polynomial:

$$\alpha(x) = a_{21}x^5 + a_{22}x^4 + a_{23}x^3 + a_{24}x^2 + a_{25}x + a_{26} \quad (7)$$

3. $0.082 \text{ mm} \leq x < 0.5 \text{ mm}$: this section was fit using a 10th order polynomial with coefficients ranging from highest to lowest ranked polynomial terms as $\alpha_{31}, \alpha_{32}, \dots, \alpha_{39}, \alpha_{310}$.
4. $x \geq 0.5 \text{ mm}$: The last section was described by a constant thermal expansion coefficient, α_{41} .

It should be stated that the selection of the x value bounds on these different curves were selected with the constraint that each section pieced together would represent the overall optimized thermal expansion distribution. Each piecewise function minimized the Euclidean norm (sum of squares error) within its x value bounds. The constants of the two Gaussian PDFs curve were found using a Gauss Newton numerical approach [85] and the constants of the polynomial functions were found using the built in MATLAB “polyfit” function [86]. The constants used for each curve section are listed in Table 1 and the resulting fitting, again, is shown on the right hand side of Fig. 5. These curve demarcations and functional form bounds were chosen for convenience. Any number of functional forms could be used. For example, one could use Eureka [87,88] to give any number of solutions to this eigenstrain distribution. The main purpose of doing these demarcations is so that we can input these functional forms into the

Table 1
Constants used to fit functional form for thermal expansion coefficients as a function of specimen depth.

Curve 1		Curve 2		Curve 3		Curve 4	
Var.	Value	Var.	Value	Var.	Value	Var.	Value
A	0.00051	a_{21}	−4021918	a_{31}	−5450	a_{41}	−0.00227
μ_B	0.0241	a_{22}	147844	a_{32}	14866		
σ_C	0.00764	a_{23}	−26104	a_{33}	−17603		
D	0.00227	a_{24}	15814	a_{34}	11861		
μ_E	0.0377	a_{25}	−580	a_{35}	−5007		
σ_F	0.0130	a_{26}	8.58	a_{36}	1373		
G	0.0557			a_{37}	−24.8		
H	0.0025			a_{38}	27.4		
				a_{39}	−1.79		
				a_{310}	0.0549		

crystal plasticity User MATerial (UMAT) subroutine and induce a given amount of eigenstrain as a function of depth from the surface.

2.2.3. Application to polycrystal plasticity model

Using a similar finite element model as previously described for the J_2 plasticity model, a combined crystal plasticity and J_2 plasticity model was constructed as illustrated in Fig. 6. The polycrystalline grain structure within the crystal plasticity region is constructed using a random sequential adsorption algorithm similar to that described in [71,89,90]. This spherical packing algorithm offers more control over grain sizing as compared to a traditional random seed Voronoi tessellation, which results in a normal distribution. The values of $\mu = 0.1$ and $\sigma = 0.4$ were chosen for the target lognormal grain size (mean grain size = $34 \mu\text{m}$) distribution function, $f(x; \mu, \sigma) = \frac{1}{x\sigma\sqrt{2\pi}} \exp\left[-\frac{(\ln x - \mu)^2}{2\sigma^2}\right]$, based on previous publications of fine grain IN100 grain size distributions [71,90–92]. An example of the target grain size distribution and the actual grain size distribution created using the spherical packing algorithm is shown in Fig. 6(a). These grain size distributions are normalized by the mean grain volume, $\langle V_{grn} \rangle = 4/3\pi(0.034 \text{ mm})^3 = 1.65 \times 10^{-3} \text{ mm}^3$.

Fig. 6(b) shows an isometric view of an example polycrystalline grain structure used for the FEM application of residual stresses. In this Figure, each grain is represented by a different color to visualize the grain structure. The FEM model is a square prism of material with a cross section that is 0.17 mm by 0.17 mm , which corresponds to having approximately five grains through the y and z thicknesses of the cross section. Crystal plasticity is employed for elements that are within 0.35 mm of the surface and J_2 plasticity is employed for elements that are at a distance greater than 0.35 mm from the surface to the total x dimension, which is 1 mm in this case.

Fig. 6(c) shows a scaled side view of the example polycrystalline line grain structure shown in Fig. 6(b) overlaid on top of the target residual stress profile to compare the assigned FEM material behavior and mesh refinement to the target residual stress profile as a function of depth from the surface. As shown in Fig. 6(c), the refinement in mesh was selected to correspond to key areas in the

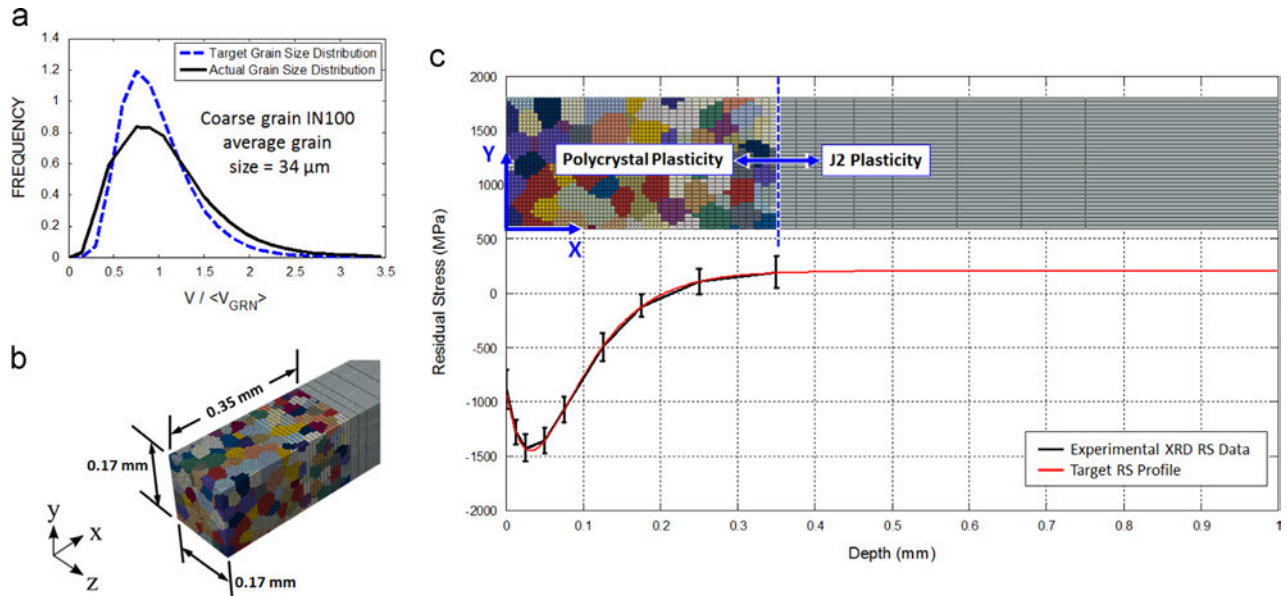


Fig. 6. Example combined polycrystals plasticity and J_2 plasticity finite element model used for eigenstrain-based application of residual stresses. Crystal plasticity is used for depths of $x \leq 0.35 \text{ mm}$ and J_2 plasticity for $x > 0.35 \text{ mm}$. The experimental XRD residual stress profile is from Buchanan et al. [25] and the target residual stress profile is given by Eq. (2). (a) Target versus actual gain size distribution using random sequential adsorption algorithm, (b) Isometric view of example polycrystalline grain srtructure used for FEM application of residual stress, and (c) scaled side view of example polycrystalline grain structure in (b) overlaid on target RS profile to show assigned material behaviour and and mesh refinement as a function of depth from the surface.

residual stress profile. Since a mesh size of $5\ \mu\text{m}$ provided convergence for the FEM response, this mesh size was used for elements that were within the compressive residual stress zone, $x \leq 0.2\ \text{mm}$ from the surface. Since the experimental residual stress was given up to a depth of $x=0.35\ \text{mm}$, the crystal plasticity zone was extended up to this depth also. Beyond this depth of $x=0.35\ \text{mm}$, the residual stress field is relatively flat; thus, J_2 plasticity was used for the zone of $x > 0.35\ \text{mm}$ and the mesh size slowly coarsened out to the depth of $x=1\ \text{mm}$.

2.3. Method to impose single load/unload sequence

The boundary and loading conditions used during the single, uniaxial load/unload sequence to study residual stress relaxation are shown in Fig. 7. Fig. 7(b) shows 2D projections of the 3D FEM model (Fig. 7(a)) as viewed from the surface (left) and side (right). The loading step starts from the condition where the $x=0$ surface constraint has been released and the stresses in the model have been allowed to relax normal to the surface (ref. bottom left hand side of Fig. 5). Periodic boundary conditions are applied to the lateral surfaces (at $z=0$ and $z=0.17\ \text{mm}$) using a multi point *Equation constraint in ABAQUS [75]. The bottom surface at $y=0$ and the surface at full FEM depth ($x=1\ \text{mm}$) are constrained from normal displacement during the load/unload sequence. Rigid body rotation and translation are prevented by constraining z direction displacement for 4 nodes located at coordinates $(x,y,z)=\{(0, 0, 0), (0, 0.17\ \text{mm}, 0), (1\ \text{mm}, 0, 0), (1\ \text{mm}, 0.17\ \text{mm}, 0)\}$; these 4 node locations are denoted in Fig. 7(b) by the green filled black circles. With these boundary conditions applied, the top surface ($y=0.17\ \text{mm}$) of the model is subjected to a given net normal traction, $\sigma_{yy,net} = \sigma_a$, and then unloaded to $\sigma_{yy,net} = 0\ \text{MPa}$. During this loading process the top surface is subjected to a multi point constraint (MPC) to make all of the nodes on the top surface displace the same throughout the deformation process.

A MPC displacement controlled method is used for residual stress relaxation studies because residual stress relaxation is most pertinent to strain controlled conditions, e.g., notches. The magnitude of residual stress relaxation will vary depending on the

maximum load or displacement applied. Consequently, we study the effect of maximum load/displacement on residual stress relaxation.

3. Results and discussion

3.1. Contour plots of stress in specimens

Fig. 8(b) (e) shows example stress contour plot results for the polycrystalline grain structure depicted in Fig. 8(a). The left hand column of this Figure shows contours of the σ_{yy} component of stress and Von Mises stress at the end of eigenstrain application with all finite element surfaces constrained (upper left of Fig. 5) and the right hand column shows these same contour plots after the surface constraint is released so the outer tractions become zero (lower left of Fig. 5). For comparison purposes, the contour plot scales of the σ_{yy} component plots (Fig. 8(b) and (c)) are identical as well as the contour plot scales for the Von Mises plots (Fig. 8(d) and (e)). These Figures display the ability of the FEM model to induce compressive residual stresses using constrained thermal expansion.

The first thing that is immediately noticed from this contour plot is the high value of σ_{yy} stress (or more precisely, the hydrostatic stress) induced near the surface as the eigenstrain is applied and the faces are constrained (Fig. 8(b)). This high value of hydrostatic stress is typical for a component that is loaded in constrained compression. It is also well known that when a component is loaded in constrained compression, larger strain (or equivalently stress) is required for yielding as opposed to an unconstrained compression condition. In fact, constrained compression can increase the apparent yield strength by a factor of two as compared to unconstrained compression. In these constrained compression cases, a better indicator of plastic response is to use a deviatoric (or equivalent) stress measurement. Hence, both the σ_{yy} and Von Mises stress measures are shown in these plots. Although during the constrained compression step the maximum compressive stress is $\sigma_{yy} = 3868\ \text{MPa}$, the Von Mises

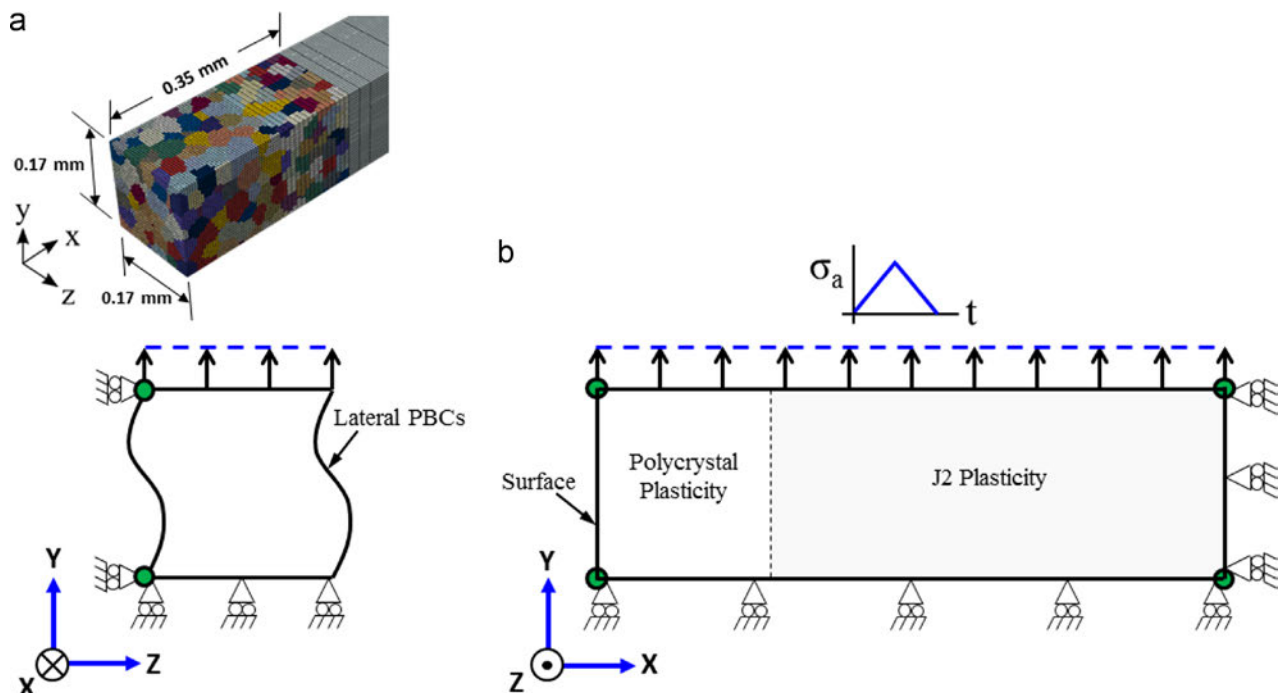


Fig. 7. Schematic of boundary and loading conditions used for single load/unload residual stress relaxation studies. (a) 3D FEM model showing polycrystalline grain structure, and (b) 2D projection of FEM model as viewed from the surface (left) and side (right).

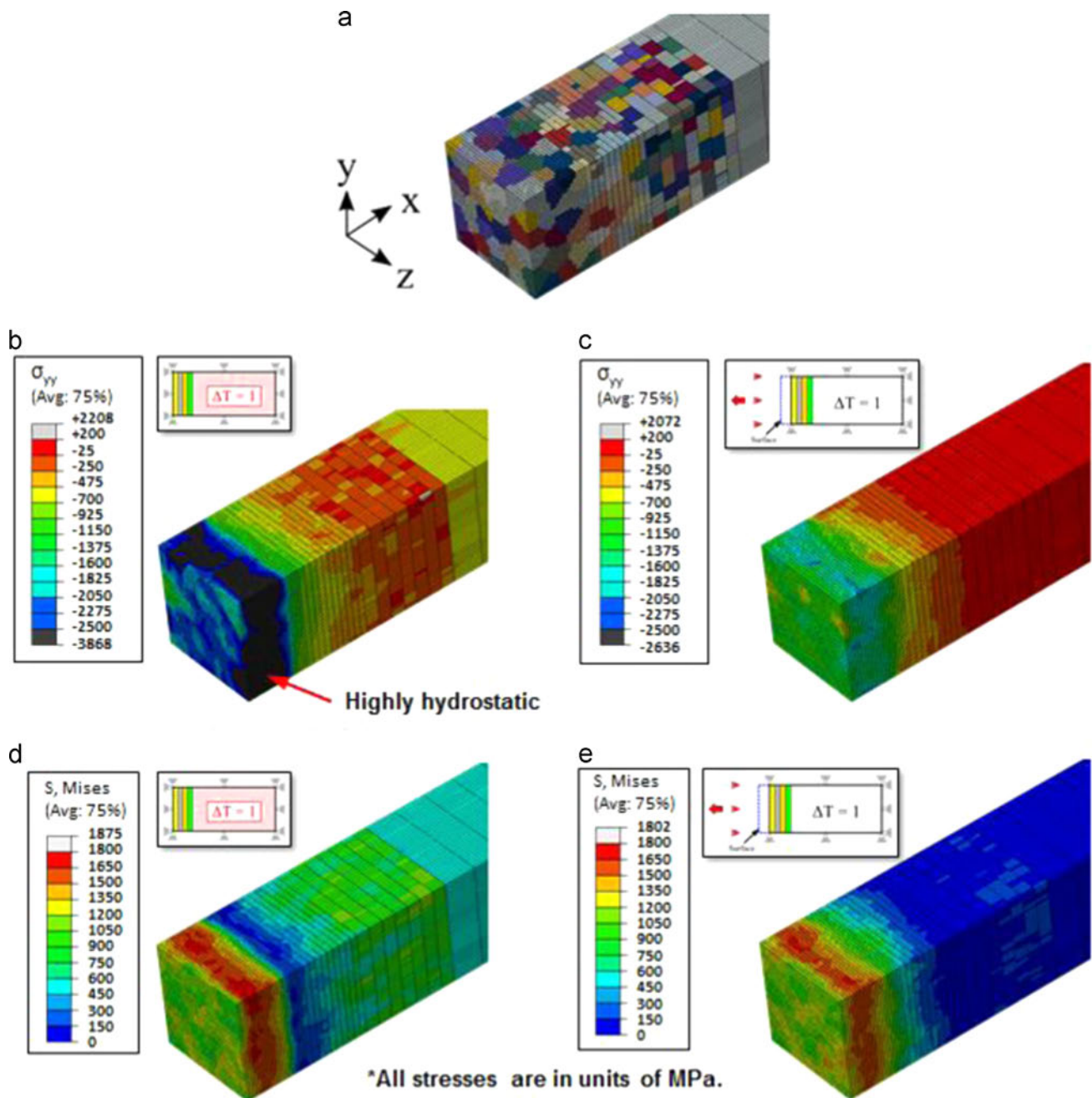


Fig. 8. Example stress contour plot results for conditions before and after surface constraint released. All stresses are in units of MPa. (a) Initial polycrystalline grain structure (0.17 mm x 0.17 mm square cross-section), (b) Contour of σ_{yy} at end of eigenstrain application with all faces constrained, (c) Contour of σ_{yy} after surface constraint has been released, (d) Contour of VM stress at end of eigenstrain application with all faces constrained, and (e) Contour of VM stress after surface constraint has been released.

equivalent stress is at a more reasonable maximum value of 1875 MPa.

The release of the surface constraint on the $x=0$ face (ref. the bottom left portion of Fig. 5) allows the finite element model to expand in the negative x direction. Subsequently, the stress component in the x direction (σ_{xx}) tends toward zero and the σ_{yy} and σ_{zz} components settle into the desired biaxial residual stress values. It should also be noted that after relaxation of the normal surface traction on $x=0$ face, all slices normal to the surface also have net zero σ_{xx} traction into the depth.

3.2. Scatter in residual stress among multiple realizations

In this section, the results from $N=5$ instantiations are presented to determine the amount of scatter exhibited among

multiple digitally created microstructures. Due to the different orientation distribution of the grains, the residual stress value of an element at a given depth will differ depending on the orientation of the grain in which the element is located and its interactions between its neighbor grains. Therefore, certain combinations of microstructures will cause the overall residual stress profile to deviate above or below a given ideal/target mean stress value. Plotted in Fig. 9(a) are results from one random microstructure instantiations. In this Figure, each red dot indicates the residual stress value within a single element. Clearly, there is significant scatter in the elemental residual stress values, especially in the near surface area where compressive residual stresses are highest. Since the finite element model employs a structured, voxelated mesh, the residual stress component values at each finite depth (x distance) are averaged and depicted with a blue and green

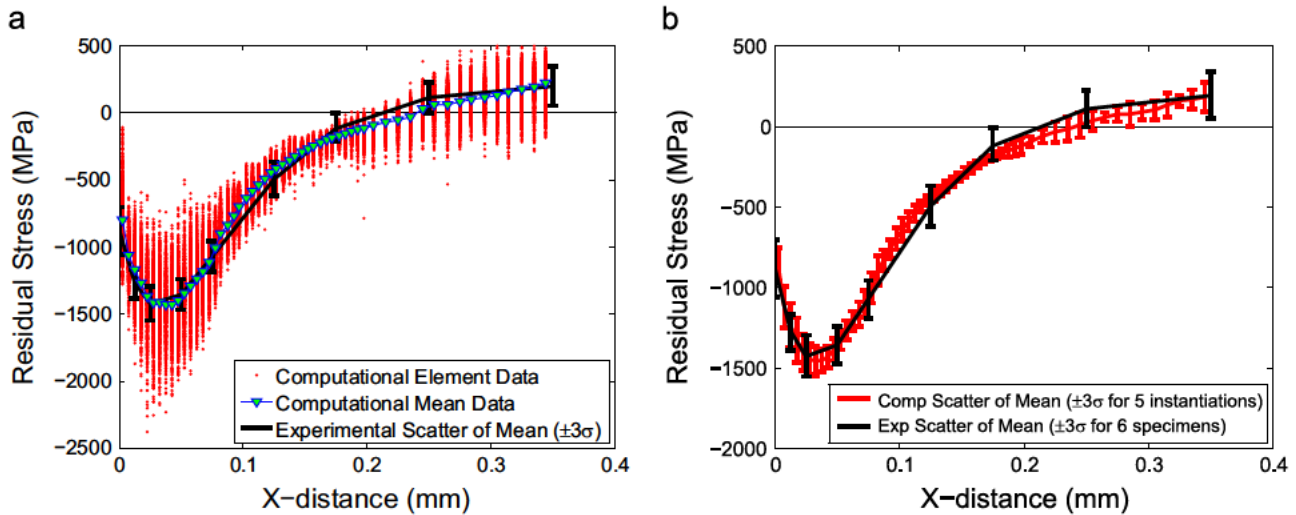


Fig. 9. Computational versus experimental residual stress profile as a function of depth from the surface. Experimental data are from Buchanan et al. [25]. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.) (a) Instantiation 1, and (b) Scatter in RS profile for 5 computational instantiations versus scatter in experimental RS data.

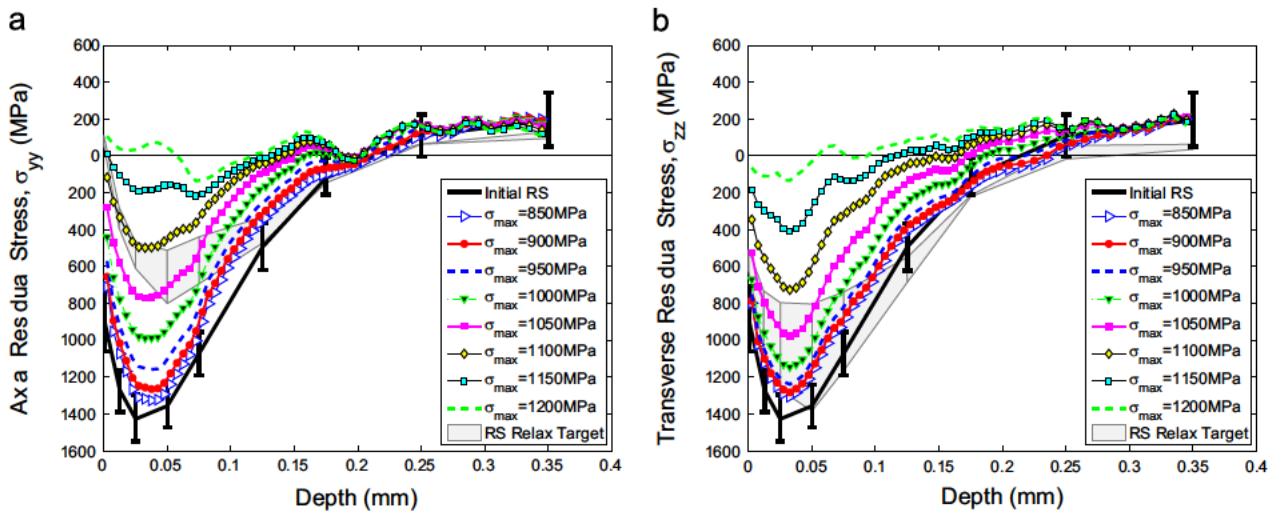


Fig. 10. Simulated residual stress relaxation due to a single load/unload sequence as a function of maximum applied stress. The experimental residual stress target relaxation data measured after one cycle are from Buchanan [45]. (a) Axial direction (σ_{yy}). (b) Transverse direction (σ_{zz}).

triangle. Additionally, the target residual stress profile from Buchanan [45] is depicted by the thick black error bar lines. The error bar lines indicate the scatter in average residual stress from six different specimens, where the average residual stress from each specimen is found over an irradiated area of $3 \text{ mm} \times 5 \text{ mm}$ [45]. It is clear from this plot that the eigenstrain method of computationally inducing residual stresses within the crystal plasticity framework results in residual stress profiles that are able to match experimental mean values.

Fig. 9(b) compares the experimental data from six baseline XRD measurements [45] to the statistical spread from $N=5$ random instantiations using the polycrystal plasticity model. The typical definition of the standard deviation from a small population are invoked for these $\pm 3\sigma$ values. As shown in Fig. 9(b), there is a strong correlation between the statistical spread of the mean value found from experiments and the statistical spread of the mean value predicted by the crystal plasticity simulations for the near surface ($x < 0.1 \text{ mm}$) residual stress values. Based on only $N=5$ instantiations, the computational model slightly underpredicts the scatter for locations further into the depth of the smooth specimen. However, the current and future studies focus on the role of

residual stresses in suppressing crack formation/propagation near the surface. Therefore, we conclude that the method used here adequately supports these current and future residual stress studies. The utility of this model will further be explored with respect to residual stress relaxation in the following section.

3.3. Residual stress relaxation with single load/unload results

Here we compare the simulated relaxation of residual stresses to experimental residual stress relaxation studies on a coarse grain IN100 at 650°C with average grain size of $25 \mu\text{m}$ [45]. Buchanan [45] presented the residual stress relaxation of two specimens in the axial (y loading axis) direction and transverse (z) direction due to a single stress controlled load/unload sequence with $\sigma_{\text{max}} = 900 \text{ MPa}$ (Ref. [45, Fig. 51]). The spread in XRD measurements of experimental residual stress relaxation in the axial and transverse directions are used for comparison to the simulated residual stress relaxation results presented here.

Pictured in Fig. 10 is the retained σ_{yy} and σ_{zz} residual stress values as a function of depth and maximum applied stress following the simulated load/unload sequence. The top portion

of this Figure shows the relaxation of the axial (σ_{yy}) stress and the bottom portion shows relaxation of the transverse (σ_{zz}) stress due to the single load/unload sequence. As in previous Figures, the initial residual stress is denoted by the thick black error bars. Also, the gray shaded regions in Fig. 10 (a) and (b) correspond, respectively, to the axial and transverse target residual stress relaxation profiles measured by XRD after unloading [45].

The overall trend of the relaxation curves is as expected: there is an increase in residual stress relaxation as the maximum applied stress is increased. When the maximum stress reaches a value of approximately $\sigma_{max} = 1150$ MPa, the effect of residual stresses are totally negated in the axial direction. As the peak stress increases to a value of $\sigma_{max} = 1200$ MPa, the axial residual stresses become tensile at the surface and go into compression further into the depth ($x > 0.4$ mm, which is not depicted in these plots) of the model. Although this depth ($x = 0.4$ mm) at which the computational model transitions from tensile to compressive stress is slightly different than the experimental one ($x = 0.2$ mm [14], the fact that the computational model predicts this reversal of residual stresses is promising.

Comparing the gray shaded target residual stress relaxation zone (from [45, Fig. 51]) to the computational relaxation curves, there is slight difference in curve shape at depths in the range of $x = 0.05$ mm to $x = 0.2$ mm. The computational model predicts more relaxation (relatively speaking) in this region as compared to the experimentally measured relaxation in this region. The reason for this difference is currently unknown, but potential reasons for this discrepancy are discussed in the “Limitations” section below.

The predicted residual stress relaxation at the surface of the specimen in the range of $x < 0.05$ mm seems to follow the experimental trend, despite the error in the range of $x = 0.05$ mm to $x = 0.2$ mm. In the surface region, the peak stress required to get in the range of the experimental residual stress relaxation is around $\sigma_{max} = 1000$ – 1050 MPa for the axial direction and $\sigma_{max} = 1100$ MPa in the transverse direction. Since there were a range of values of peak stress that resulted in residual relaxation comparable to experiments, a single peak stress value of $\sigma_{max} = 1050$ MPa was used for assessing RS relaxation behavior scatter.

The same $N = 5$ instantiations that were used for the residual stress profile scatter in Fig. 9(b) were used to assess scatter of residual stress relaxation. In separate FEM simulations, these finite element models were loaded up to a maximum stress value of

$\sigma_{max} = 1050$ MPa and then unloaded to zero stress along the y direction. The average residual stress profiles were obtained in the axial and transverse directions. From these values, the statistical spread of the axial and transverse retained residual stresses are plotted in Fig. 11. In this Figure, the left and right columns contain the retained axial and transverse residual stresses, respectively, for maximum applied stress values of 1050 MPa. These simulated values are compared to the statistical spread from 2 separate residual stress relaxation experimental samples from the experimental XRD data reported in Buchanan [45]. Compared to the experimental residual stress profiles [45], the scatter in residual stress of the computational profiles seems to be within a factor of 2 of the experimental profiles. However, this conclusion is quite preliminary as there were only a limited number ($N = 2$) of data points from the experiments; it is expected that with more data points, the scatter in residual stress relaxation data would decrease. Further advancement of the residual stress relaxation model would be possible with more experimental and computational replicas.

In the current relaxation study, we only considered relaxation during the first loading cycle. It is well known that relaxation with fatigue cycling occurs in two stages [21]: the majority of residual stress relaxation occurs during the first cycle followed by gradual relaxation with continued fatigue cycling. This two stage relaxation process has been reported for multiple materials in several experimental [93–95] and computational [21,96,97] studies on residual stress relaxation. In the work of Prasannavenkatesan et al. [20,21], they considered the effects of shot peening induced surface residual stresses, pores, and hard and soft primary inclusions in martensitic gear steel on nonlocal fatigue indicator parameters (FIPs) and fatigue crack formation near the inclusions. They concluded that residual stress relaxation could only be modeled using polycrystal plasticity [21].

3.4. Limitations of the CPFEM relaxation model

There are several limitations in this model that can cause errors in the relaxation simulations. First, the computational model contains a domain decomposition of the material into crystal plasticity and J_2 plasticity models. Although these two models were calibrated to the same set of experimental data, the difference in anisotropic crystal plasticity and isotropic J_2 plasticity can cause differences in material stress/strain behavior over the range

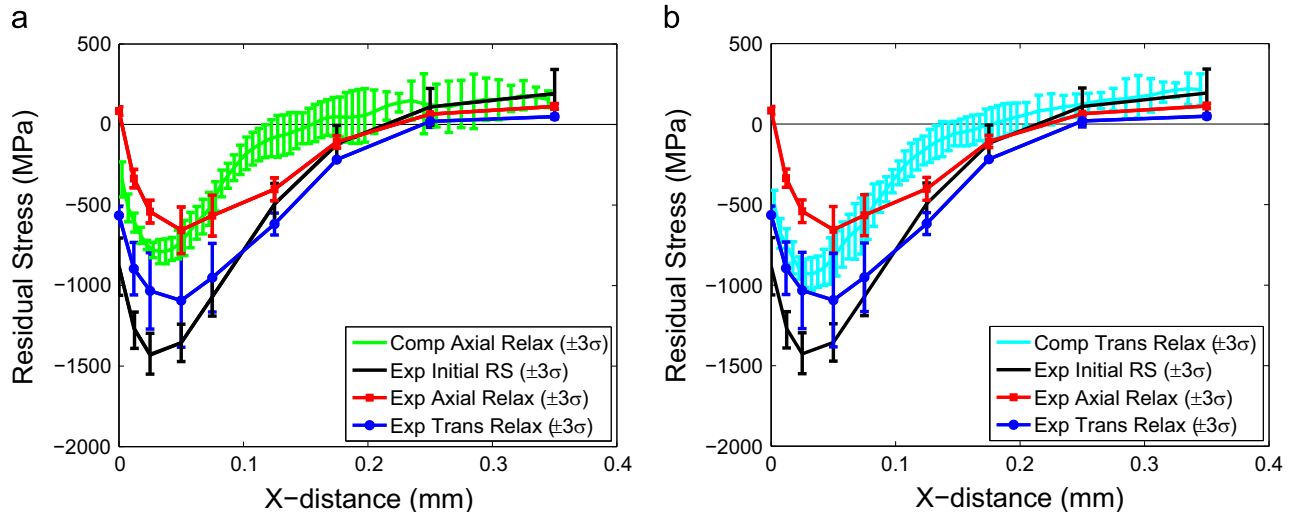


Fig. 11. Simulated versus experimental scatter in residual stress relaxation due to a single load/unload sequence for maximum applied stress $\sigma_{max} = 1050$ MPa for $N = 5$ instantiations. The experimental residual stress scatter data are from Buchanan [45]. (a) Axial (σ_{yy}) relaxation, $\sigma_{max} = 1050$ MPa, and (b) Transverse (σ_{zz}) relaxation, $\sigma_{max} = 1050$ MPa.

of several grains. For example, Fig. 9(b) shows that the mean residual stress behavior averaged over a bin size of $x=5\text{ }\mu\text{m}$, $y=0.17\text{ }\mu\text{m}$, and $z=0.17\text{ }\mu\text{m}$ can vary up to $\sim 200\text{--}250\text{ MPa}$. This scatter further increases when averaging over individual elements (Fig. 9(a)) or the scale of individual grains. On the other hand, a J_2 plasticity FEM model smears the effect of material anisotropy and predicts a single residual stress profile as a function of depth with no scatter. Additionally, it should be noted that these material models were fit to a coarse grain IN100 with a slightly larger grain size ($34\text{ }\mu\text{m}$) than the IN100 microstructure used for the residual stress experiments ($25\text{ }\mu\text{m}$).

Another potential source of error could be due to the fact that this model is a quasi static representation of a dynamic shot peening process. Shot peening involves high speed collision of many shot beads against a surface. The current model does not take into account such dynamic effects as elastic wave propagation, high strain rate effects, or inertia effects; Incorporation of these effects has been shown to provide better residual stress prediction compared to that of a quasi static analysis [26–28]. Additionally, the intense amount of cold working and resulting dense dislocation network produced at the surface can invoke plasticity induced refinement of the microstructure in the surface layer [45,98]. Finer grain structure can affect the yield point/strength of the material in the thin, highly plastically deformed surface layer; this change in yield point could significantly alter the elastic plastic response of the whole model. This refinement in the microstructure was not accounted for in this work. However, the purpose of the current model was to simulate the overall induced mechanical response due to shot peening, rather than individual impact events or grain refinement.

Regardless of these limitations, the current framework is able to reproduce essential aspects of the initial residual stress profile, scatter, and relaxation. While the total profile of the residual stress relaxation curves do not agree precisely with experiments, the simulated relaxation trends near the surface correlate well with experiments. Therefore, the current quasi static eigenstrain application of residual stresses is deemed reasonable for assessing the effect of residual stresses and microstructure on fatigue variability.

4. Summary

In this work, a framework is presented for imposing shot peened residual stresses using computational crystal plasticity. The residual stresses are induced by a distribution of imposed quasi thermal expansion eigenstrains. This distribution was first fit to an experimentally measured residual stress curve using an isotropic J_2 plasticity material behavior and then applied within a crystal plasticity finite element constitutive model. Good correlation between computational and experimental values were obtained for (1) the initial residual stress profile, (2) the scatter in the initial residual stress profile among multiple instantiations, and (3) near surface residual stress relaxation trends for a single load/unload cycle. This method of coupling the effect of microstructure and residual stresses can be used to investigate the effect of certain microstructural features (such as the largest grain, inclusions, pores, etc.) on microstructure sensitive fatigue estimation.

Acknowledgments

WDM is thankful for funding from the Air Force Research Laboratory, United States under contract FA8650 09 2 5800 with the Southwestern Ohio Council for Higher Education. WDM would also like to acknowledge helpful technical discussions with Dennis Buchanan, Reji John, and Andy Rosenberger regarding this work.

DLM is grateful for the support of the Carter N. Paden, Jr. Distinguished Chair in Metals Processing.

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